

EAST Search History

EAST Search History (Prior Art)

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	2	("20050000543").PN.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	OFF	2010/06/01 09:11
L2	101958	((robot\$3 or vehide or mobile or autonomous) near4 (travers\$4 or rout\$3 or path\$3 or travel\$4 or mov\$3)) and (sprial\$3 or circ\$3 or curl\$3 or coil\$3 or whorl\$3 or screw\$3 or helical\$4)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2010/06/01 10:00
L3	14816	L2 and ((travers\$4 or rout\$3 or path\$3 or travel\$4 or mov\$3) with (adjacent\$3 or next or neighbor\$3 or side) with (cell or area or square or portion or partition or zone or subcell or subarea or block or squarezone or subcell or subarea or block))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2010/06/01 10:00
L4	2452	L3 and ((travers\$4 or rout\$3 or path\$3 or travel\$4 or mov\$3) near4 (sprial\$3 or circ\$3 or curl\$3 or coil\$3 or whorl\$3 or screw\$3 or helical\$4))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2010/06/01 10:01
L5	774	L4 and ((travers\$4 or rout\$3 or path\$3 or travel\$4 or mov\$3) near4 (sprial\$3 or circ\$3 or curl\$3 or coil\$3 or whorl\$3 or screw\$3 or helical\$4)) with (next or adjacent\$3 or neighbor\$3 or side)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2010/06/01 10:02
L6	147	L5 and map\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2010/06/01 10:03

L7	6164	((robot\$3 or autonomous\$3 or mobile or vehicle) near4 (travers\$4 or travel\$4 or path or rout\$3 or trajector\$4)) and ((percent\$4 or densit\$3 or denseness or quantity or crowded\$4) near4 (cell or area or portion or zone or subcell or subarea or block or square))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2010/06/01 10:41
L8	2501	L7 and map\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2010/06/01 10:41
L9	1276	L8 and ((status or state or clean\$3 or unclear\$3 or \$3travel\$4 or \$3travers\$3 or classifi\$3 or label\$3) near4 (cell or area or portion or zone or subcell or subarea or block or square))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2010/06/01 10:43
L10	327	L9 and ((percent\$4 or densit\$3 or denseness or quantity or crowded\$4) same ((status or state or clean\$3 or unclear\$3 or \$3travel\$4 or \$3travers\$3 or classifi\$3 or label\$3) near4 (cell or area or portion or zone or subcell or subarea or block or square)))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2010/06/01 10:44
L11	273	L10 not protein	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2010/06/01 10:45
L12	1	("2008/0147473").URPN.	USPAT	OR	ON	2010/06/01 10:52
L33	46	318/568.12.ccls. and ((map\$4 or trajector\$3 or rout\$3 or path or movement) with (subgrid or grid or table or hatch or cell or matrix or checker or patch\$3)) and (sprial\$3 or cird\$3 or curl\$3 or coil\$3 or whori\$3 or screw\$3 or helical\$4)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2010/06/01 12:00
L34	1881	701/23.ccls.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2010/06/01 12:01

L35	42	L34 and ((robot\$3 or autonomous\$3 or mobile or vehicle) near4 (travers\$4 or travel\$4 or path or rout\$3 or trajector\$4)) and ((percent\$4 or densit\$3 or denseness or quantity or crowded\$4) near4 (cell or area or portion or zone or subcell or subarea or block or square))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2010/06/01 12:01
L36	266	701/26.ccls.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2010/06/01 12:01
L37	12	L36 and ((travers\$4 or rout\$3 or path\$3 or travel\$4 or mov\$3) near4 (spiral\$3 or circle\$3 or curl\$3 or coil\$3 or whorl\$3 or screw\$3 or helical\$4))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2010/06/01 12:01
L38	526	701/25.ccls.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2010/06/01 12:02
L39	205	L38 and ((status or state or clean\$3 or unclean\$3 or \$3travel\$4 or \$3travers\$3 or classifi\$3 or label\$3) near4 (cell or area or portion or zone or subcell or subarea or block or square))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2010/06/01 12:02
L40	65	L39 and (spiral\$3 or circle\$3 or curl\$3 or coil\$3 or whorl\$3 or screw\$3 or helical\$4)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2010/06/01 12:02
L41	381	700/253.ccls.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2010/06/01 12:03
L42	28	L41 and ((map\$4 or trajector\$3 or rout\$3 or path or movement) with (subgrid or grid or table or hatch or cell or matrix or checker or patch\$3)) and (spiral\$3 or circle\$3 or curl\$3 or coil\$3 or whorl\$3 or screw\$3 or helical\$4)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2010/06/01 12:03
L43	2486	700/245.ccls.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2010/06/01 12:04

L44	145	L43 and ((map\$4 or trajector\$3 or rout\$3 or path or movement) with (subgrid or grid or table or hatch or cell or matrix or checker or patch\$3)) and (sprial\$3 or cirdl\$3 or curl\$3 or coil\$3 or whorl\$3 or screw\$3 or helical\$4)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2010/06/01 12:04
S123	93269	(map\$4 with (subgrid or grid or table or hatch or cell or matrix or checker or patch\$3)) and (rout\$3 or path or trajector\$3)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2010/05/28 15:20
S124	41561	S123 and (robot\$3 or vehicle or mobile or autonomous)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2010/05/28 15:42
S125	39935	S124 and (obstruct\$4 or object or block\$3 or fill\$3)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2010/05/28 15:43
S126	17017	S124 and ((obstruct\$4 or object or block\$3 or fill\$3) near4 (cell or area or portion or zone or subcell or subarea or block or square))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2010/05/28 15:45
S127	1856	S126 and ((robot\$3 or vehicle or mobile or autonomous) near5 (path or rout\$3 or travers\$3 or trajector\$4))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2010/05/28 15:45
S128	1147	S127 and (percent\$4 or densit\$3 or denseness or quantity or crowded\$4)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2010/05/28 15:47
S129	407	S128 and ((percent\$4 or densit\$3 or denseness or quantity or crowded\$4) near4 (cell or area or portion or zone or subcell or subarea or block or square))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2010/05/28 15:47
S130	2	("20070156283").PN.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	OFF	2010/05/28 17:30

S131	101889	((robot\$3 or vehicle or mobile or autonomous) near4 (travers\$4 or rout\$3 or path\$3 or travel\$4 or mov\$3)) and (sprial\$3 or cird\$3 or curl\$3 or coil\$3 or whorl\$3 or screw\$3 or helical\$4)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2010/05/31 17:20
S132	12354	S131 and ((travers\$4 or rout\$3 or path\$3 or travel\$4 or mov\$3) near4 (sprial\$3 or cird\$3 or curl\$3 or coil\$3 or whorl\$3 or screw\$3 or helical\$4))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2010/05/31 17:23
S133	277	S132 and (map\$4 with (subgrid or grid or table or hatch or cell or matrix or checker or patch\$3))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT	OR	ON	2010/05/31 17:24

EAST Search History (Interference)

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L13	894	701/23.ccls.	USPAT; UPAD	OR	ON	2010/06/01 11:52
L14	75	L13 and (map\$4 with (subgrid or grid or table or hatch or cell or matrix or checker or patch\$3))	USPAT; UPAD	OR	ON	2010/06/01 11:52
L16	11	L13 and ((percent\$4 or densit\$3 or denseness or quantity or crowded\$4) same ((status or state or clean\$3 or unclean\$3 or \$3travel\$4 or \$3travers\$3 or classifi\$3 or label\$3) near4 (cell or area or portion or zone or subcell or subarea or block or square)))	USPAT; UPAD	OR	ON	2010/06/01 11:53
L17	104	L13 and ((percent\$4 or densit\$3 or denseness or quantity or crowded\$4) and ((status or state or clean\$3 or unclean\$3 or \$3travel\$4 or \$3travers\$3 or classifi\$3 or label\$3) near4 (cell or area or portion or zone or subcell or subarea or block or square)))	USPAT; UPAD	OR	ON	2010/06/01 11:54
L18	397	701/25.ccls.	USPAT; UPAD	OR	ON	2010/06/01 11:54

L19	23	L18 and ((travers\$4 or rout\$3 or path\$3 or travel\$4 or mov\$3) near4 (sprial\$3 or circI\$3 or curl\$3 or coil\$3 or whorI\$3 or screw\$3 or helical\$4))	USPAT; UPAD	OR	ON	2010/06/01 11:54
L20	44	L18 and (map\$4 with (subgrid or grid or table or hatch or cell or matrix or checker or patch\$3))	USPAT; UPAD	OR	ON	2010/06/01 11:55
L21	200	701/26.cds.	USPAT; UPAD	OR	ON	2010/06/01 11:55
L22	318	700/253.cds.	USPAT; UPAD	OR	ON	2010/06/01 11:55
L23	29	L22 and ((travers\$4 or rout\$3 or path\$3 or travel\$4 or mov\$3) with (sprial\$3 or circI\$3 or curl\$3 or coil\$3 or whorI\$3 or screw\$3 or helical\$4))	USPAT; UPAD	OR	ON	2010/06/01 11:56
L24	57	L22 and ((map\$4 or trajector\$3 or rout\$3 or path or movement) with (subgrid or grid or table or hatch or cell or matrix or checker or patch\$3))	USPAT; UPAD	OR	ON	2010/06/01 11:57
L25	1272	700/245.cds.	USPAT; UPAD	OR	ON	2010/06/01 11:58
L26	105	L25 and ((travers\$4 or rout\$3 or path\$3 or travel\$4 or mov\$3) with (sprial\$3 or circI\$3 or curl\$3 or coil\$3 or whorI\$3 or screw\$3 or helical\$4))	USPAT; UPAD	OR	ON	2010/06/01 11:58
L27	61	L25 and ((travers\$4 or rout\$3 or path\$3 or travel\$4 or mov\$3) near5 (sprial\$3 or circI\$3 or curl\$3 or coil\$3 or whorI\$3 or screw\$3 or helical\$4))	USPAT; UPAD	OR	ON	2010/06/01 11:58
L28	203	L25 and ((map\$4 or trajector\$3 or rout\$3 or path or movement) with (subgrid or grid or table or hatch or cell or matrix or checker or patch\$3))	USPAT; UPAD	OR	ON	2010/06/01 11:58
L29	78	L25 and ((map\$4 or trajector\$3 or rout\$3 or path or movement) with (subgrid or grid or table or hatch or cell or matrix or checker or patch\$3)) and (sprial\$3 or circI\$3 or curl\$3 or coil\$3 or whorI\$3 or screw\$3 or helical\$4)	USPAT; UPAD	OR	ON	2010/06/01 11:59
L30	160	318/568.17.cds.	USPAT; UPAD	OR	ON	2010/06/01 11:59

L31	636	318/568.12.ccls.	USPAT; UPAD	OR	ON	2010/06/01 11:59
L32	37	L31 and ((map\$4 or trajector\$3 or rout\$3 or path or movement) with (subgrid or grid or table or hatch or cell or matrix or checker or patch\$3)) and (sprial\$3 or cird\$3 or curl\$3 or coil\$3 or whorl\$3 or screw\$3 or helical\$4)	USPAT; UPAD	OR	ON	2010/06/01 11:59
L46	332	((robot\$3 or autonomous\$3 or mobile or vehicle) near4 (travers\$4 or travel\$4 or path or rout\$3 or trajector\$4)) and ((percent\$4 or densit\$3 or denseness or quantity or crowded\$4) near4 (cell or area or portion or zone or subcell or subarea or block or square)).clm.	USPAT; UPAD	OR	ON	2010/06/01 12:05
L47	16	L46 and ((map\$4 or trajector\$3 or rout\$3 or path or movement) with (subgrid or grid or table or hatch or cell or matrix or checker or patch\$3)).clm.	USPAT; UPAD	OR	ON	2010/06/01 12:05

6/ 1/ 2010 2:50:06 PM

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